SrlApi

Srl API is your gateway to the system resources.

Logging

Log API let you define message levels. Levels allow you to let your debug code in the source, and only compile it when needed.

In order, levels are:

- NONE
- TRACE
- DEBUG
- MAX

When writing your software, you decide what level the message is for. When compiling or running you software, you decide what minimal level your code must have to be printed.

- `srl_log(level, "message")` prints a message
- `srl_log_printf(level, "message_with_format", arguments...)` prints a printf-like message

Arguments in printf-like version may be not evaluated if level is not sufficient. Therefore you **MUST NOT** put expressions with side effects in the parameter list. ie do **not** do this:

```
srl_log_printf(DEBUG, "i=%d\n", i++);
```

Mwmr Communication Channels

- `srl_mwmr_t channel = GET_ARG(port_name)` defines a local variable associated to a MWMR channel acces port. The `port_name` argument corresponds to the port name defined in the task model defined in the DSX description.

- `srl_mwmr_read(channel, local_buffer, size)` reads `size` 32-bit words from the MWMR channel to the local buffer. The `local_buffer` argument is a `void*`. The `size` argument must be a multiple of the channel width.

- `srl_mwmr_write(channel, local_buffer, size)` writes `size` 32-bit words from the local buffer to the MWMR channel. The `local_buffer` argument is a `void*`. The `size` argument must be a multiple of the channel width.

Locks

- `srl_lock_lock( lock )` takes a lock, waiting if necessary
- `srl_lock_unlock( lock )` releases the lock

Barriers

- `srl_barrier_wait( barrier )` waits for a barrier-global synchronization

Other APIs

- `srl_busy_cycles( N )` tells the simulation environment the simulation should run at least N cycles while in this call. This makes sense only for virtually synthetised tasks, otherwise, this call is a noop.
- `srl_mwmr_config( controller_name, reg_n, value )` puts value `value` in config register `reg_n` of specified controller
- `srl_mwmr_status( controller_name, reg_n )` reads status register `reg_n` of specified controller, returns a int32_t
- `srl_assert( cond )` checks `cond` is true, fatally fails otherwise