Around revision [900], MutekH got support for Flattened device trees.

Rationale

Flattened device trees (FDT) are useful to get a list of all available hardware where no hardware-based enumeration exists (aka PnP, like PCI, USB, ... provides).

FDT provides normalized representation of the hardware platform without adding specific initialization code.

The normalization comes from IEEE1275 (aka Open Firmware); while Open Firmware also defined heavy things (like a Forth interpreter), we only use the FDT information.

Using FDT is mainstream, is also used by Linux and BSD, supported by U-Boot and other bootloaders.

References

- You may learn many things <u>?googling</u> for "flattened device tree".
- The dtc utility used to compile .dts files in MutekH is mainteained at <u>?http://git.jdl.com/</u>. You may:
 - Browse the git there <u>?http://git.jdl.com/gitweb/</u>
 - Download a snapshot <u>?http://git.jdl.com/software/</u> This repository also includes some documentation and a reference library for handling FDTs.
- The Linux kernel documentation tree contains <u>?an useful document</u> about device trees (Documentation/powerpc/booting-without-of.txt)

Implementation

In MutekH, FDT is handled through an hardware enumerator device driver, it behaves like the other enumerators (PCI, ISAPnP).

MutekH-Specific Node syntax quick reference

Processors

Processor nodes look like:

```
Mips,32@0 {
    name = "Mips,32";
    device_type = "cpu";
    reg = <0>;
};
```

req

```
This is the CPU identification number
device_type
must be "cpu"
```

There is a couple of optional attributes:

ipi

This is a reference to the ICU device handling IPIs for this CPU, and the ipi number, like

```
ipi = <&{/xicu@0/out@2} 2>;
```

Memories

Memory nodes look like:

```
memory@0 {
    device_type = "memory";
    cached;
    reg = <0x61100000 0x00100000>;
};
```

device_type

must be "memory"

reg

must be a couple of <address size> with both the values respecting #address-cells and #size-cells.

There are two optional attributes:

cached The memory is cacheable coherent

The memory is cached and coherent (cached is implied, setting it is optional)

References to interrupt controllers

Interrupts controller are referenced from one node to another in order to describe the interrupt tree. References are handled through the following properties:

irq

Must be a path to an existing ICU device, and the icu irq number, enclosed in $< \{ path \}$ no>. This syntax is mandatory. Example:

```
irq = <&{/cpus/Mips,3200} 0>;
```

Example:

```
icu@0 {
    device_type = "soclib:icu";
    input_count = <2>;
    reg = <0x20600000 0x20>;
    irq = <&{/cpus/Mips,32@0} 0>;
};
tty@0 {
    device_type = "soclib:tty";
    tty_count = <1>;
    reg = <0x90600000 0x10>;
    irq = <&{/icu@0} 1>;
};
```

Here the ICU device for /tty@0 is /icu@0 (device at address 0x20600000), which in turn references /cpus/Mips, 32@0 as its ICU device.

The /chosen node

The /chosen node contains informations about the global system peripherals and configuration. In MutekH, we use the /chosen node to reference preipherals:

timer

Select the global timer device root Select the root file system device console Select the console tty

Referencing the correct devices does not implicitly make their drivers available. You still have to select the driver in your configuration file.

Example:

```
chosen {
    console = &{/tty@0};
    root = &{/ramdisk@0};
};
```

Parameter structure construction for calling _init functions

Some devices require a structure containing parameters in order to correctly initialize them. This case is handled in the FDT description. Let's see the example of the soclib:xicu component. It needs a structure containing:

```
struct xicu_root_param_s
{
        size_t input_lines;
        size_t ipis;
        size_t timers;
};
```

In the driver, the id definition is:

This informs the FDT parser this device will need a parameter structure, with the parameters described in the xicu_param_binder correctly filled-in.

In this table, there is one entry telling the output_line_no parameter is an integer.

Available data types are:

```
PARAM_DATATYPE_INT
    a simple integer
PARAM_DATATYPE_DEVICE_PTR
    a device reference (&{/node/path} in the device tree source), which will be transparently translated to
    a struct device_s * before filling the structure. Device must exist in the tree.
PARAM_DATATYPE_ADDR
    an address, #address-cells will be honored
PARAM_DATATYPE_BOOL
    a simple boolean, i.e. a property with no value, if present it is true, if absent it is false (like the cached
    attribute in memory nodes)
```

Example

Drivers may export themselves as FDT-aware, and define which device name string to match. For instance, the following subtree defines a tty device:

```
tty@0 {
    device_type = "soclib:tty";
    tty_count = <1>;
    reg = <0x90600000 0x10>;
    irq = <&{/icu@0} 1>;
};
```

In turn, the SoCLib tty driver declares itself (in source:trunk/mutekh/drivers/device/char/tty-soclib/tty-soclib.c#L146) as:

Note there is no parameter structure definition, so the two last arguments of DEVENUM_FDTNAME_ENTRY are 0.

```
static const struct devenum_ident_s
                                       tty_soclib_ids[] =
{
       DEVENUM FDTNAME ENTRY ("soclib:tty", 0, 0),
        { 0 }
};
const struct driver_s tty_soclib_drv =
{
  .class
                       = device class char,
  .id_table
                       = tty_soclib_ids,
  .f_init
                       = tty_soclib_init,
                     = tty_soclib_cleanup,
  .f_cleanup
  .f_irq
                       = tty_soclib_irq,
 .f.chr = {
   .f_request
                   = tty_soclib_request,
  }
};
```

This will make the FDT enumerator use the correct driver, matching "soclib:tty"